

# **Altimetry Applications to Transboundary River Basin Management**

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**Keywords:** transboundary river, river management, altimetry, flood forecasting, hydrologic modeling

## Abbreviations

ABN	L’Autorité du bassin du Niger (Niger Basin Authority)
CNES	Centre National d’Études Spatiales
CSA	Canadian Space Agency
Envisat	Environmental Satellite
ERS-2	European Remote Sensing Satellite-2
ESA	European Space Agency
EUMETSAT	European Organisation for the Exploitation of Meteorological Satellites
FFWC	Flood Forecasting and Warning Center
GBM	Ganges-Brahmaputra-Meghna
GFO	Geosat Follow-On
GMES	Global Monitoring for Environment and Security
GOHS	Geodesy, Oceanography and Hydrology from Space
HEC-RAS	Hydrologic Engineering Center-River Analysis System
IAHS	International Association of Hydrological Sciences
HYCOS	Hydrological Cycle Observing System
ISRO	Indian Space Research Organisation

IWM	Institute of Water Modeling
Jason-1/2	Joint Altimetry Satellite Oceanography Network-1/2
JERS-1	Japanese Earth Resources Satellite-1
KaRIN	Ka-band Radar Interferometer
LEGOS	Laboratoire d'Études en Géophysique et Océanographie Spatiales
MODIS	Moderate Resolution Imaging Spectroradiometer
NASA	National Aeronautics and Space Administration
NOAA	National Oceanic and Atmospheric Administration
Poseidon	Positioning, Ocean, Solid Earth, Ice Dynamics, Orbital Navigator
RMSE	Root Mean Square Error
SAR	Synthetic Aperture Radar
SARAL	Satellite with ARGOS and AltiKa
SRTM	Shuttle Radar Topography Mission
SWOT	Surface Water and Ocean Topography
TFDD	Transboundary Freshwater Dispute Database
TOPEX	TOPography Experiment
T/P	TOPEX/Poseidon
UNECA	United Nations Economic Commission for Africa
UNEP	United Nations Environment Programme
USDA	United States Department of Agriculture
WCD	World Commission on Dams

## 1. Introduction

In order to meet basic human needs for freshwater, accurate estimates of temporal and spatial variations in river discharge, as well as the water stored in lakes, wetlands, and manmade reservoirs, are essential. However, current in situ networks do not adequately observe these variables globally, and prospects for their expansion are not promising (e.g., Shiklomanov et al. 2002; IAHS 2001; Stokstad 1999). Furthermore, many of the world's largest river basins, in terms of discharge, contain vast wetlands that lack flow convergence, thus leading to highly uncertain estimates of their discharge, and contributing to uncertainty in the most basic quantities

in the global water balance, such as the runoff from the continents to the oceans.

Physical limitations on in situ networks are further exacerbated by the hydro-politics of transboundary rivers, i.e., those rivers that cross one or more international boundaries. Most political boundaries do not match the topographically-determined boundaries of river basins. As a result, more than 260 major river systems worldwide cross international political boundaries (Wolf et al., 1999; Fig. 1). Today, transboundary rivers account for more than 50% of global streamflow, and, based on 2007 estimates, more than 40% of the world's population lives in transboundary river basins (Wolf et al., 1999; Oregon State University, 2013; Oak Ridge National Laboratory, 2008; U.S. Census Bureau, 2013). Water management activities in the headwaters of transboundary river basins can have vital implications for water supply in other nations in the downstream regions. The World Commission on Dams (WCD, 2000) reports that there have been at least 45,000 large dams built since the 1930s worldwide. It is estimated that half of the world's major rivers have at least one dam somewhere within their drainage area (WCD, 2000). With a changing climate and increasing water scarcity due to population growth and economic development (Vörösmarty et al., 2005; Gleick, 2002), more reservoirs are likely to be commissioned or maintained (rather than removed) in this century in order to secure reliable supplies of fresh water for human use. Recent examples of constructed or planned reservoirs on major transboundary rivers include the Gabčíkovo-Nagymaros Project built on the Danube River by Slovakia (formerly Czechoslovakia) in Europe, the Southeast Anatolia Project or GAP (Turkish acronym) plan in Turkey for reservoirs in the headwaters area of the Euphrates river in Asia, and the Namibian plan to impound water from the Okavango River in Africa (De Villiers, 2000).

Fig. 1: Location of the world's major rivers (blue lines labeled with river names) and transboundary river basins (colored based on the number of countries that contain a portion of the basin). Countries per basin and transboundary basin boundaries are a product of the Transboundary Freshwater Dispute Database (TFDD), Department of Geosciences, Oregon State University, updated to include Southern Sudan. Additional information about the TFDD can be found at: <http://www.transboundarywaters.orst.edu>.

Historically, information about reservoir storage (or level) and releases has been controlled by nations in which the reservoir and river reaches are located. Without adequate treaties for transboundary cooperation for water resources management at operational time scales (Balthrop and Hossain, 2010), the controlling nation has no legal obligation to share reservoir storage and release information with downstream nations in a timely manner. This has made forecasting water supply and flooding in some downstream nations a challenging task (Hossain and Katiyar, 2006). Balthrop and Hossain (2010) and Bakker (2009) argue that even with bilateral treaties and comprehensive ground networks among all riparian nations, the issue of water resources monitoring and flood hazard warning will always remain fundamentally elusive.

## **2. Advances in Satellite Altimetry**

Since the launch of Seasat in 1978, satellite altimetry has been used to monitor the heights of the world's oceans. Through a long heritage of altimetry (see chapter 1 by Benveniste, this volume), the ability to measure heights over some large lakes, reservoirs, and rivers was developed. Which water bodies are observed and at what frequency depends on the satellite orbits, the instrument characteristics, and, over land, the size of the water bodies and their surrounding topography (Crétaux and Birkett 2006; Calmant et al. 2008). At present, however, observations of inland water bodies are generally limited to large water bodies. Satellite observations are independent of political boundaries, in contrast to in situ networks, which are primarily managed at the national scale. For this reason, satellite altimetry data are potentially useful in the context of transboundary water issues, as a complement to existing in situ networks. Satellite altimetry data could add valuable information for regions with no gages or for which

ground measurements are not shared or are unreliable, even given limitations due to the overpass time frequency and coverage.

Current nadir altimeters provide one-dimensional measurements of water elevation along the satellite ground tracks, which typically are separated by several hundred km. These limitations are reduced somewhat during periods when multiple satellites have been in orbit. For example, during the years 2002 to 2010 several radar altimeters were in orbit for overlapping periods: TOPEX/Poseidon (TOPography Experiment/Positioning, Ocean, Solid Earth, Ice Dynamics, Orbital Navigator) (T/P, 1992-2005), Jason-1 (2002-2011), Envisat (Environmental Satellite) (2002-2012), Geosat Follow-On (GFO, 2002-2008) and Jason-2 (2008-present) (USDA 2014). Such nadir altimeter constellations make it possible to monitor a large number of lakes and rivers with temporal sampling that is considerably improved relative to the pre-2002 period for the largest inland water bodies. As a part of the capacity-building efforts of the European Union's new Copernicus program (formerly known as Global Monitoring for Environment and Security, GMES), a panel of new satellites, dedicated to land monitoring from multispectral sensor, Sentinel-2, and radar altimetry in dual Ku-C bands (12-18 GHz and 4-8 GHz electromagnetic bands, respectively), Sentinel-3, has been planned for the next few years. Sentinel-3 will be composed of a pair of satellites (Sentinel-3A and Sentinel-3B), with the first launch expected between 2014 and 2015. In addition to the Sentinel series, early 2013, the Centre National d'Études Spatiales (CNES) and Indian Space Research Organisation (ISRO) launched the SARAL (Satellite with ARGOS and AltiKa)/AltiKa mission, which is the first altimeter operating in Ka-band, the portion of the electromagnetic spectrum at 26.5-40 GHz. The main advance of SARAL/AltiKa is a better spatial resolution than previous instruments due to the radar signal's smaller footprint, which allows better discrimination of water in small lakes and reservoirs and in anastomosed rivers with a large number of small channels. In the future, CNES, the European Organisation for the Exploitation of Meteorological Satellites (EUMETSAT), the National Oceanic and Atmospheric Administration (NOAA) and the National Aeronautics and Space Administration (NASA) will continue the Jason (Joint Altimetry Satellite Oceanography Network) program, with the launch of the Jason-3 radar altimeter. More information on upcoming satellite missions is included in chapter 6 (Benveniste, this volume). Considered separately, these missions will not significantly alleviate the problem noted above of sparse and infrequent crossings of inland water bodies, but taken together, in synergy with other

remote sensing techniques, like satellite imagery, they will enhance satellite altimetry's role in surveying and predicting the hydrological regime of the world's major rivers, including the transboundary ones. An important characteristic of these new missions for water management purposes is that all but SARAL/AltiKa have been developed for use in an operational framework.

Notwithstanding the development of the new nadir altimeters described above, coverage in space and time of all but the largest inland water bodies remains problematic. Furthermore, nadir altimeters provide information only about the water surface height, and not extent, both of which are necessary for estimation of storage change, a critical variable for water management. For this reason, a new satellite mission, the Surface Water and Ocean Topography (SWOT) mission, is under development jointly by the U.S. (NASA) and France (CNES), with support from Canada (Canadian Space Agency, CSA). SWOT is intended to monitor, over essentially all land areas of the globe, the surface elevations and extents of water bodies with surface areas larger than about 1 km<sup>2</sup> during each satellite repeat period (22 days<sup>1</sup>). In addition, SWOT will provide unprecedented spatial resolution in the open ocean and near coastal waters that will help to resolve ocean circulation anomalies (eddies) at much smaller spatial scales than is possible with nadir altimeters. The result over the global land areas will be unprecedented spatial resolution for monitoring of inland water bodies, and two-dimensional maps (as contrasted with tracks from nadir altimeters) of water surface elevations. Methods have been proposed to estimate streamflow based on SWOT observations of water surface elevation, water surface slope, and river width; these approaches include data assimilation into hydrodynamics models, an optimization based on continuity and Manning's equation, and properties implicit to downstream hydraulic geometry (e.g., Andreadis et al. 2007; Biancamaria et al. 2011a; Durand et al. 2014; Yoon et al. 2012; and chapter 4 by Durand et al., this volume). At the equator, most water bodies will be observed two times per 22 days (the satellite repeat period), but observations will be much more frequent at high latitudes (Fig. 2). SWOT will be the first satellite mission dedicated to the observation of both the oceanic and continental water surfaces. SWOT is currently planned for launch around 2020.

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<sup>1</sup> Although the planned orbit at the time that this document was prepared had a 22-day repeat period, the project has since decided to use a 21-day repeat period. All figures presented here are based on a 22-day repeat period; the implications of the difference in planned orbit for most of the results shown herein are modest. Also note that the exact location of each satellite swath will depend on the timing of launch.

Fig. 2: Number of SWOT observations per 22-day repeat period over the global land areas.

The main SWOT payload will be a Ka-band wide swath radar interferometer (KaRIN; Ka-band Radar Interferometer). Two antennas, separated by a 10-m boom will result in two 50-km-wide ground swaths on each side of nadir, separated by a 20 km gap (Fig. 3). The area between the two swaths may be partially covered by a separate nadir altimeter. KaRIN's intrinsic pixel resolution will vary from 70 m (near range) to 10 m (far range) across-track and will be at best around 5 m along-track (this value will be a function of decorrelation time). Temporal decorrelation comes from changes of the observed surface between consecutive observation times. The Synthetic Aperture processing technique uses multiple "looks" at a given point on the surface to improve the image's resolution, and as a result, if the surface changes very quickly (i.e., short decorrelation time due to a choppy water surface), the image resolution will be coarser. In the end, the pixels will be averaged which will result, for each 1 km<sup>2</sup> in surface water area, in accuracy of at least 10 cm in water surface elevation (Rodríguez 2012). The relative error in surface extent using the SWOT water mask will be less than 20% of the total water body area (Rodríguez 2012). Table 1 summarizes SWOT science requirements for hydrology. At present, the nominal SWOT orbit is a 78° inclination and 22-day repeat period, which implies that the KaRIN instrument will observe at least 90% of the global land area between 78°N/S and that the satellite will fly over the same point every 22 days. However, considering the total 140-km swath width, many locations will be seen at least twice during one repeat period (Fig. 2).

Fig. 3: The Surface Water and Ocean Topography (SWOT) satellite antennas and instruments. Image courtesy of C. Lion and B. Reinier; the initial image concept is from Karen Wiedman. The satellite image used is from CNES, and image in the swaths are Landsat images.

Table 1: SWOT hydrology science requirements (for more details, see Rodríguez 2012).

The new measurements that SWOT will provide have potentially far-reaching implications for transboundary rivers, as the observations are not constrained by international



boundaries. The major questions motivated by the SWOT mission in the context of transboundary rivers are:

- How will globally and freely available reservoir storage, streamflow, and water level information produced by SWOT affect the management of water resources in a changing climate?
- Will this change in data availability help to resolve what are in some cases now fundamentally intractable problems, such as real-time forecasting of transboundary streamflow, management of transboundary water resources in a basin-wide manner, and equitable allocation of water resources for riparian nations?
- Will nations in transboundary river basins become more independent and sovereign in their ability to forecast and manage water resources flowing from and to other nations?
- Will the increased transparency of information increase trust among nations for greater cooperation on transboundary water issues?

Some recent studies suggest that there is a direct relationship between the institutional capacity of nations to gather surface water information and the effectiveness of operational water resources management, particularly in the area of transboundary flooding (Bakker 2009).

In the remainder of this chapter, we explore three transboundary case studies in Asia and Africa to show how satellite altimetry (current generation nadir altimeters and the proposed SWOT swath altimeter) can potentially overcome the limitations of current in situ observations in the context of transboundary rivers.<sup>2</sup> Our discussion focuses primarily on altimetric measurements of river levels, though it is worth noting that important benefits are anticipated from the remote sensing of reservoir storage change as well. In the first case, the Ganges-Brahmaputra-Meghna (GBM) basins, the potential for improved flood forecasting in Bangladesh based on currently available altimetry data has been demonstrated in an operational context (Hossain et al. 2013; Papa et al. 2012), and swath altimetry from the Shuttle Radar Topography Mission (SRTM) has been used to estimate streamflow (Jung et al. 2010; Woldemichael et al. 2010). In the second case, a single currently operational altimeter, Jason-2, is able to provide

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<sup>2</sup> The Amazon River basin is an excellent example of a transboundary river basin in which altimetry observations have shown a great deal of potential. However, insofar as chapter 11 (Calmant et al., this volume), is dedicated to inland altimetry applications in the Amazon River basin, we do not discuss the Amazon in this chapter.

sparse observations of the Indus River; however, it is expected that new missions like Sentinel-3A/-3B and SWOT will provide valuable information about the effects of the construction and operation of planned reservoirs in the basin's headwaters. In the third case, the countries of the Niger River basin support joint management and planning; however, a lack of infrastructure for monitoring and transmitting in situ hydrologic data limits these efforts. Studies suggest that altimetry data can supplement the existing in situ observations to and will lead to improved modeling and predictions in the Niger basin (e.g., Pedinotti et al. 2012). In the cases of the GBM and the Niger River, existing altimetry data have been used to complement in situ monitoring networks to aid in water management in transboundary basins, and in all cases, further advances are expected to result from even greater data availability from the upcoming SWOT mission.

### **3. Ganges-Brahmaputra-Meghna Basins**

The GBM river basins are primarily located in India (62% of basin area), China (20%), Nepal (9%), and Bangladesh (7%) (Oregon State University 2013). Because Bangladesh lies at the mouth of this massive river system, it receives more than 90% of its surface water from nations upstream in the GBM (Nishat and Rahman 2009). Bangladesh is particularly susceptible to flooding because floodplains comprise approximately 80% of its land area; furthermore, flooding in Bangladesh is expected to increase due to sea level rise associated with climate change (Ahmad and Ahmed 2003). The hydroclimatology of the GBM is strongly driven by the June-October monsoon, which produces nearly 85% of Bangladesh's rainfall; however, the most intense floods occur when flood peaks travel across national boundaries through two or more rivers simultaneously (Ahmad and Ahmed 2003). Because data is effectively not shared between India, which has the largest contributing drainage area, and Bangladesh, the Bangladesh government has very little advance notice of likely flood conditions. Furthermore, several cases of dam construction further complicate the ability to predict flood conditions because dams mean that river flows are dependent not only on precipitation, which can be estimated from existing satellites, but also on human decisions. Some examples of basin "replumbing" include the recently revived mega-project concept by the Indian Government called the Indian River Linking Project. This project proposes to divert surface water from humid northern regions to the arid southern regions through a network of canals and dams connecting the rivers of Brahmaputra and

Ganges (Misra et al. 2007). Some other pertinent examples are the Farakka barrage (on Ganges river; Mirza 1998), Gozaldoba Barrage (on Teesta River – a tributary of Brahmaputra; Nishat and Faisal 2000), and the now-shelved Tipaimukh Dam (on the Meghna River in India; Sinha 1995).

On the Ganges and Brahmaputra Rivers, flood waves propagate from the uplands downstream to Bangladesh over the course of several days. Nadir altimetry has the potential to forecast water levels in Bangladesh based on satellite crossings of the river further upstream (Fig. 4). Biancamaria et al. (2011b) showed that because most of the streamflow is generated in the upper reaches of the Ganges and Brahmaputra Rivers, water levels are highly correlated along the lower reaches of the rivers. They found using T/P altimetry, forecasts of water level anomalies at 5-day and 10-day lead times are possible with Root Mean Square Error (RMSE) of around 0.40 m and 0.60-0.80 m, respectively, depending on which virtual stations were used. Higher RMSE values were estimated for the Ganges River because correlations on the Ganges are degraded somewhat by local and short-term variations in water level due to its lower mean annual flow. They also identified options for constraining forecast errors and extending forecast lead times by including information from weather, hydrological, and hydrodynamic forecasts, as well as by adding data from multiple altimeters. Over the same river basin, Papa et al. (2012) used a combination of T/P, ERS-2 (European Remote Sensing Satellite-2), Envisat, and near real-time Jason-2 data to reconstruct long-term time series of river discharge in the delta, using past in situ data (over the Ganges and the Brahmaputra). The river discharge estimates were then used as inputs to model ocean circulation in the Bay of Bengal, which is important in improved understanding of salinity in the Bay of Bengal, which is linked to regional climate variability.

Fig. 4: Map of Ganges and Brahmaputra Rivers, showing the (1992-2002) T/P ground track and river crossings, as well as the river gauges used as water level forecasting points in Biancamaria et al. (2011b). Figure adapted from Biancamaria et al. (2011b).

The approach of Biancamaria et al. (2011b) was extended by Hossain et al. (2013), who tested an operational forecasting system based on Jason-2 altimetry data on the Ganges-Brahmaputra Rivers. They tested forecasting capabilities at 17 locations for which the Flood Forecasting and Warning Center (FFWC) of the Bangladesh government issues official water

level forecasts at a 3-day lead time. In this system, Hossain et al. (2013) used historic Jason-2 river crossings (virtual stations) to develop rating curves between in situ measurements of discharge at Hardinge Bridge and Bahadurabad and water levels at the virtual stations upstream. For each day, a 5-day forecast of discharge at these two sites was developed from the most recent Jason-2 observations. These discharge forecasts provided the upstream boundary conditions to the 1-D hydrodynamic model, Hydrologic Engineering Center-River Analysis System (HEC-RAS, version 4.0; developed at the Hydrologic Engineering Center, a division of the Institute of Water Resources at the U.S. Army Corps of Engineers; <http://www.hec.usace.army.mil/software/hec-ras/>), that was implemented in Bangladesh by Siddique-E-Akbor et al. (2011). The HEC-RAS hydrodynamic model was used to propagate the 5-day lead forecast discharge to the 17 FFWC sites.

The forecast water levels from the Jason-2 5-day forecast were compared to the “5-day later” nowcast water levels, which were estimated by using in situ observations as boundary conditions to the HEC-RAS model. Hossain et al. (2013) found that the 5-day forecasts were able to capture the same trends and peak events as the nowcasts. In fact, because the HEC-RAS model tended to overestimate water levels and the Jason-2 forecast tended to underestimate discharge at Hardinge Bridge and Bahadurabad, the 5-day forecasts slightly better matched in situ river level data.

The results of this proof-of-concept study were tested in real-time operational water level forecasting, performed by the staff of the Institute of Water Modeling (IWM), Dhaka, Bangladesh. Over the period from 1 Aug. 2012 to 20 Aug. 2012, average forecast errors, compared to in situ observed water levels at Bahadurabad and Sirajganj on the Brahmaputra River and Hardinge Bridge on the Ganges River, ranged from -0.4 m to 0.4 m. The skill of the 5-day Jason-2 based forecasts was more accurate during this period than the standard 5-day later nowcast (Hossain et al. 2013). Interested readers wishing to access this real-time operational flood forecasting system that is managed entirely by a stakeholder agency are referred to <http://apps.geoportal.icimod.org/BDFloodforecasting> and <http://apps.iwmbd.com/satfor>.

Fig. 5 shows Sentinel-3A/-3B ground tracks on the Ganges-Brahmaputra basins, showing improved coverage from the constellation of these nadir altimeters compared to a single altimeter, like T/P or Jason-2. The distance between ascending (or descending) tracks for T/P and Jason-2 is 315 km at the equator. The distance between two ascending (or descending) tracks for

one of the Sentinel-3 satellite's is 104 km at the equator; however, the distance between one ascending (or descending) track of Sentinel-3A and the adjacent ascending (or descending) track of Sentinel-3B is only 52 km. One result of the improved coverage of Sentinel-3 is that there will be more virtual stations (river crossings) at a wider range of distances from the in situ stations. This should improve forecasting over a range of lead times. Also, when a virtual station has a temporal gap in its data record, which could result from errors in the tropospheric correction, retracking algorithm, or instrument errors (Biancamaria et al. 2011b), the higher density of virtual stations increases the likelihood of a neighboring station having a useable observation sooner than the next overpass.

Fig. 5: Map of Ganges and Brahmaputra Rivers, showing the Sentinel-3A and -3B ground tracks.

While nadir altimetry as exploited by Hossain et al. (2013) enables a robust approach to operational flood forecasting in this hydrological region, further opportunities are expected with the advent of swath-based satellite altimetry. Jung et al. (2010) and Woldemichael et al. (2010) demonstrate the application of SRTM-derived elevations and water surface slope, Landsat-derived water mask, and in situ measurements of bathymetry to estimate instantaneous discharge along the Brahmaputra River. Jung et al. (2010) used Manning's equation with a constant roughness coefficient of 0.025 and were able to estimate discharge with an error of only 2.3%, relative to in situ gage discharge, by averaging satellite-based discharge estimates at four cross sections within 24-km flow distance of the gage. Upon closer examination, Woldemichael et al. (2010) identified three distinct outliers in these estimates along the river length. They suggested two primary sources of error: 1) errors in the water mask and 2) errors in the assumed Manning's roughness coefficient.

In the approach employed by Jung et al. (2010), the water mask from Landsat is used to identify the SRTM heights that are attributable to water for the purposes of slope estimation and also—in combination with the in situ bathymetry data—for the calculation of cross-sectional area and hydraulic radius. Woldemichael et al. (2010) addressed the water mask errors by testing a set of data filtering schemes to enforce a relatively uniform water level along each channel cross section; they find that filtering for the minimum water level across a transect produces the best estimates of discharge. Because SWOT's high incidence angle enhances the return signal

from water surfaces, SWOT will be able to provide concurrent measurements of water surface elevation and a water mask, which should minimize these types of classification errors. Woldemichael et al. (2010) also note that calibration of Manning's roughness with gage discharge, where available, can improve discharge estimates along a given reach.

An alternative forecasting method, which is more complex and computationally intensive than those discussed above, is to assimilate altimetric observations into a hydrology or hydraulic model. For example, Michailovsky et al. (2013) developed and applied an Ensemble Kalman Filter to adjust predictions from a routing model of the main reach of the Brahmaputra River (forced with a calibrated rainfall/runoff model) by assimilating Envisat observations, over the 2008-2010 period. With this method, the discharge Nash-Sutcliff coefficient increased from 0.78 (no assimilation) to 0.84 (with assimilation) and discharge RMSE improved by over 15% in the first 4 days after assimilation of altimetric observations. This method seems promising, but it has not yet been used operationally for transboundary basins. More discussion of assimilation of altimetry data is included in chapter 15 by Bauer-Gotwein et al., this volume.

#### **4. Indus Basin**

The Indus basin (Fig. 6) drains 1,140,000 km<sup>2</sup> and is shared among Pakistan (53% of the watershed), India (34%), China (7%) and Afghanistan (6%) (Wolf et al. 1999; Oregon State University 2013). More than 300 million people live in the basin, mainly in Pakistan (190 million) and India (110 million) (Oregon State University 2013; Oak Ridge National Laboratory 2008). In 1960, India and Pakistan signed the Indus Waters Treaty, which defined the minimum amount of water that should be split between the two countries. At the same time, the Permanent Indus Commission was established, and 80% of the flow of the Indus was allocated to Pakistan (Bagla 2010).

Fig. 6: Map of Indus basin (green boundary) showing Jason-2 ground tracks (yellow lines).

In 2005, India began to build the Baglihar Dam (southern magenta dot on Fig. 6) on the Chenab River (Bagla 2010). Even though the Indus Waters Treaty gives full control of the Chenab River to Pakistan, it also allows India to build run-of-river power plants, as long as some

criteria are met. Pakistan has claimed that the Baglihar Dam does not fulfill these criteria. In 2007, an independent expert appointed by the Permanent Indus Commission recognized India's right to build the dam, but asked for some design changes. However, this decision did not completely resolve the issue. The timing of the filling (in August 2008) of the reservoir has been criticized by Pakistan, as it significantly decreased the flow of the Chenab River during the period of reservoir filling and thus negatively impacted farmers in Pakistan. According to India, the initial filling date of the Baglihar Dam is in agreement with the Indus Waters Treaty (Bagla 2010).

More recently, in 2009, India began construction of a dam on the Kishenganga River (northern magenta dot in Fig. 6), a tributary of the Jhelum River (Bagla 2010). However, the management of the Jhelum River is entirely assigned to Pakistan according to the Indus Waters Treaty. For this reason, Pakistan has expressed concerns about the impact of the Jhelum hydropower project on the river's discharge. Pakistan's claims have been rejected by India, and the issue was brought before the International Court of Arbitration. On Feb. 18, 2013, a Partial Award was rendered, which specifies that India may operate Kishenganga Hydro-Electric Project as a Run-of-River plant but may not reduce levels in the reservoir below its dead storage level (Permanent Court of Arbitration 2013).

The green lines on Fig. 6 correspond to Jason-2 satellite ground tracks, and show that current nadir altimeters can only provide sparse measurements of water elevations along the river network. In contrast, Sentinel-3 will have a better coverage (Fig. 7) providing measurements in near real-time. It will therefore allow estimation of the impact of the Baglihar and Jhelum dams on the river flows in real time, with data that have a homogeneous accuracy over the entire basin and that cannot be considered as biased toward one or the other of the riparian countries. As for SWOT, it will measure both elevation and surface area (hence volume) changes of each reservoir, as well as water elevation and slope variations for the Indus and its tributaries both in India and in Pakistan. Fig. 8 shows the number of SWOT observations over the study region per repeat period (i.e., during a 22 days time span). According to satellite images on Google Earth, widths of the Chenab and Kishenganga Rivers were between 40 m and 50 m in October 2003, which was during the low flow period and before the filling of the Baglihar Reservoir. Thus, SWOT might be able to provide critical information, even if not in real time, that will allow estimation of the discharge of these rivers during the high flow season (SWOT will require river

widths of 50-100 m to provide accurate estimates of river width, slope, and surface height, critical variables for discharge estimation). The Baglihar Reservoir pondage volume (i.e., the live storage for a run-of-river plant) necessary for operation should be around  $16 \times 10^6 \text{ m}^3$  and the maximum pondage should be around  $32 \times 10^6 \text{ m}^3$ , according to the independent expert appointed by the Permanent Indus Commission (Lafitte 2007). Assuming an average depth of the order of 10 m, the surface area of the reservoir should be several  $\text{km}^2$  and thus should be “seen” by SWOT.

Fig. 7: Sentinel-3A and Sentinel-3B ground tracks over the Indus basin.

Fig. 8: Number of SWOT observations per repeat period (22 days) in the Indus basin.

Because these reservoirs are located in a mountainous region (Fig. 6), some or even all SWOT images of these reservoirs might be not usable because of the surrounding mountains, which could “mask” the water surface (this effect is called layover). Layover is a geometric distortion that occurs when the radar beam reaches the top of a tall feature before it reaches the base. As a result, within the radar image, the slope of the mountain “lays over” the valley. It depends on the instrument angle of observation, mountain heights, and water extent. This issue is currently being studied at NASA and CNES. Another consideration is that the planned lifetime of the SWOT mission is relatively short (nominally 3 years), and its revisit time (which could be more than 10 days in some locations) might be problematic for some water management applications.

## 5. Niger Basin

The Niger River basin located in West Africa is shared by 10 countries: Nigeria (28%), Mali (25%), Niger (24%), Algeria (8%), Guinea (5%), Cameroon (4%), Burkina Faso (4%), Benin (2%), Ivory Coast (1%) and Chad (1%) (Wolf et al. 1999 – updated 2012; Fig. 9). Around 100 million people live inside this basin, more than half of them (67 million) in Nigeria (UNEP (United Nations Environment Programme) 2010). Most of the basin’s precipitation falls in the



southern part (Guinea and Nigeria). For example, Guinea represents 5% of the basin area, but accounts for around 30% of the basin's runoff (UNEP 2010). In the 1970s and 1980s, the Sahel region was affected by severe droughts, which had devastating impacts on agricultural self-sufficiency of the basin's population.

Fig. 9: Niger basin showing Jason-2 ground tracks.

As in the case of Bangladesh, around 90% of the waters flowing into Niger comes from upstream countries (Mali, Burkina Faso and Benin) (UNECA (United Nations Economic Commission for Africa) 2000); however, there appears to be a greater political will for data sharing in the Niger than the in the GBM basin. According to the Transboundary Freshwater Dispute Database (Oregon State University 2013), countries in the Niger River basin signed 14 international water agreements during the post-colonial period, starting in the early 1960s. Two of these focused on hydrologic monitoring and data, and one on cost-sharing. Efforts for sustainable development and environmental conservation have been incorporated into more recent agreements (Lautze et al. 2005). The Niger Basin Authority (L'Autorité du bassin du Niger, ABN, <http://www.abn.ne/>) oversees river basin planning and collects data provided by its member countries—Benin, Burkina Faso, Côte d'Ivoire, Guinea, Cameroon, Mali, Niger, Nigeria, and Chad. Beginning in 1979, the “Hydroniger Project was designed to make real-time hydrological forecasts that would be used to issue flood warnings, inform on the navigability and to facilitate dam regulation in the member countries” (Grossmann 2009). Although 65 data collection platforms in support of this effort were installed by 1987, the network began deteriorating by 1988. Current efforts are underway to restore the observation network as part of the Niger-HYCOS (Hydrological Cycle Observing System) Program. One of the most important reasons that previous attempts to build and maintain an observation network and comprehensive water management modeling system faltered was the lack of sustainable funding (Grossmann 2009). Since 2011, the nine members countries of the ABN decided any hydraulic facility with substantial impact on river flow will have to be discussed prior to its construction, coordinated by the ABN.

The Niger basin contains an inner delta (around  $-4^{\circ}\text{E}$  and  $16^{\circ}\text{N}$ ), located in Mali, where the river splits into several branches. The inner delta is the largest Western Africa wetland, along

an approximately 200-km long reach of the river, in the Sahel region. There are around one million people living in the inner delta (UNEP 2010). It is an extremely complex hydrologic system, with important evapotranspiration and infiltration fluxes; therefore, the delta highly impacts the water cycle of the entire basin. Discharge above the inner delta is almost twice as large as discharge below the delta, due largely to evaporative losses (Pedinotti et al. 2012). Goita and Diepkile (2012) showed that a “consistent long-term water level time series could be established” from three T/P tracks and eight Envisat tracks despite the complexity of the environmental conditions. On the basis of their analysis of altimetry data, they found that over a 17-year period, July-August precipitation strongly influenced the delta’s flooding processes.

In order to quantify the impact of delta flooding in the Niger, Pedinotti et al. (2012) used distributed measurements of water extent and height from remote sensing to test whether changes to processes represented by the ISBA-TRIP (Interaction Sol-Biosphère-Atmosphère-Total Runoff Integrating Pathways) model (Noilhan and Planton 1989; for details of specific implementation used, see Pedinotti et al. 2012) reflect the true spatial and temporal structure of hydrology in the region. They tested different rainfall inputs, a simple aquifer representation, and a flooding scheme in the ISBA-TRIP model with: 1) MODIS (Moderate Resolution Imaging Spectroradiometer) observations of flooded areas (Crétaux et al. 2011), 2) height changes from altimetry processed by Calmant et al. (2008) as part of the LEGOS/GOHS (Laboratoire d’Études en Géophysique et Océanographie Spatiales)/Geodesie, Oceanographie et Hydrologie from Spatiales) HYDROWEB database and 3) in situ discharge measurements provided by the ABN. They found that including aquifers in ISBA-TRIP reduced the predicted flooded fraction and better captured the duration of the floods. The inclusion of a flooding scheme improved the simulation of water level changes, as compared to altimetric observations of water levels. This work is a good example of usefulness of remote sensing data in general and altimetry data in particular, in combination with in situ measurements, to calibrate and validate hydrological models, which can be extremely useful for water managers in transboundary basins. In particular, using remote sensing data could be beneficial in studies of the inner delta because that region is extremely difficult to monitor with in situ networks and to model with current hydrological models.

One issue in simulating Niger River streamflow is that within the Niger River basin there are substantial wetland areas (mostly in the delta area) that do not contribute much runoff to the

river (Coe 1998). Areas of local ponding, including those that interact with the river, are also important contributors to evaporative losses in this basin; Nijssen et al. (2001) point out that observed flows decrease by more than 25% between Koulikoro, Mali and Gaya, Niger, despite a ten-fold increase in drainage area. Furthermore, the planned Fomi dam, to be constructed in Guinea for hydropower generation, will increase dry season discharge and decrease wet season discharge into the delta, which will likely impact the floodplain area (Liersch et al. 2012). Without knowledge of the hydrologic mechanisms and distribution of floodplain-channel interconnectivity in the delta, it is difficult to estimate the downstream implications of this construction.

As shown in Fig. 9, only two Jason-2 tracks cross the inner delta, and much of the remaining lowland areas are not observed at all. Dozens of Sentinel-3 tracks will cross the inner delta, and the greater density of tracks increases the chances of viewing ponded water bodies elsewhere (Fig. 10). Still, to map the locations of hydrologically-closed sections of the basin, and to track periods in which ponded areas might connect to the river's drainage, a water mask is needed. In the case of the inner delta, the question of connectivity between the river and ponded areas, and its impact on the hydrologic cycle of the basin as a whole, requires observations of storage change. Although space-based observations of inundated fraction are currently available, concurrent observations of height are required to quantify storage change. Jung et al. (2010) demonstrated the utility of interferometric SAR (Synthetic Aperture Radar) measurements in characterizing floodplain processes by applying Japanese Earth Resources Satellite-1 (JERS-1) measurements to map water level changes, between wet and dry seasons, in the floodplains of the Congo and Amazon Rivers. Based on relationships between water height changes, SRTM topography, and the water mask, they were able to identify fundamentally different processes and degrees of interconnectivity between each river and its neighboring wetlands. At present, altimetric studies of the Niger River wetlands have primarily focused on assessing and improving the quality of hydrologic and hydrodynamic model simulations. Similar to JERS-1, SWOT will provide concurrent measurements of the water extent and height for the entire region, but with greater frequency (1 to 2 observations over the Niger River basin per 22-day repeat period; Fig. 11) and finer spatial resolution, which will allow the identification of small-scale features, like floodplain channels. These observations should provide the opportunity to

assess spatial and temporal (monthly) variations in channel-floodplain interconnectivity in the Niger River basin.

Fig. 10: Sentinel-3A and Sentinel-3B ground tracks over the Niger basin.

Fig. 11: Number of SWOT observations per repeat period (22 days) in the Niger basin.

## 6. Conclusions

Few studies have evaluated the utility of river and reservoir height measurements from past and current nadir altimeters for transboundary water management; however, important progress has been made. There appears to be great potential as a number of new nadir altimeters are launched, especially with the new Sentinel-3 program (launch around 2014/2015) and the expected launch of SWOT later this decade. Initial testing of an operational flood prediction system in Bangladesh, based on altimetric measurements of water levels on the Ganges and Brahmaputra in India, has shown potential for improvements over the existing system based entirely on in situ data. Current generation altimeters have also played an important role in supplementing in situ observations in the calibration and validation of hydrologic models, as in the difficult-to-model Niger basin. Still, the nadir configuration of current single altimeters means that many rivers and reservoirs are poorly observed, as is the case, for instance, for the Indus basin. Similarly, for some applications, such as discharge estimation, a water mask is needed; merging imagery and heights from multiple platforms with different viewing angles and observation times introduces errors.

The problem of coverage should be dramatically improved by the advent of nadir altimeter constellations, such as Sentinel-3. Furthermore, SWOT is expected to have tremendous potential to monitor reservoir water storage change in transboundary river basins, where in a number of important cases, data are not presently available to both (or all) riparian countries. In addition to providing storage change information, SWOT will also provide river water level and slope variations over most or all of these river basins and therefore can help to assess the impact of upstream reservoirs on the downstream reaches of the river. These data will be freely

available, which could have major impacts on the nature of the management of these systems. Under the likely scenario of Sentinel-3 launching between 2014 and 2015 and SWOT becoming a reality around 2020, a current unknown is how India and Pakistan will leverage this information on storage changes and water levels of the impounded Indus basin for adaptation, mitigation and more equitable resource allocation as demand for water rises on both sides of the border. In regions like the Niger River basin, where in situ monitoring is largely cost-prohibitive, or in Bangladesh, where upstream data are not available on the GBM for political reasons, the availability of spatially distributed data from Sentinel-3 and SWOT is expected to vastly improve the knowledge base for model development and has potential for improved flood and water supply forecasting, flood mapping, model calibration and other water management applications such as reservoir operations.

## **Acknowledgements**

The digital elevation data shown as the background in Fig. 4-11 is the 2-minute Gridded Global Relief Data (ETOPO2v2) of the U.S. Department of Commerce, National Oceanic and Atmospheric Administration, National Geophysical Data Center, 2006, <http://www.ngdc.noaa.gov/mgg/fliers/06magg01.html>.

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## **Captions of tables**

Table 2: SWOT hydrology science requirements (for more details, see Rodríguez 2012).

## **Captions of figures**

Fig. 1: Location of the world's major rivers (blue lines labeled with river names) and transboundary river basins (colored based on the number of countries that contain a portion of the basin). Countries per basin and transboundary basin boundaries are a product of the Transboundary Freshwater Dispute Database (TFDD), Department of Geosciences, Oregon State University, updated to include Southern Sudan. Additional information about the TFDD can be found at: <http://www.transboundarywaters.orst.edu>.

Fig. 2: Number of SWOT observations per 22-day repeat period over the global land areas.

Fig. 3: The Surface Water and Ocean Topography (SWOT) satellite antennas and instruments. Image courtesy of C. Lion and B. Reinier; the initial image concept is from Karen Wiedman. The satellite image used is from CNES, and image in the swaths are Landsat images.

Fig. 4: Map of Ganges and Brahmaputra Rivers, showing the (1992-2002) T/P ground track and river crossings, as well as the river gauges used as water level forecasting points in Biancamaria et al. (2011b). Figure adapted from Biancamaria et al. (2011b).

Fig. 5: Map of Ganges and Brahmaputra Rivers, showing the Sentinel-3A and -3B ground tracks.

Fig. 6: Map of Indus basin (green boundary) showing Jason-2 ground tracks (yellow lines).

Fig. 7: Sentinel-3A and Sentinel-3B ground tracks over the Indus basin.

Fig. 8: Number of SWOT observations per repeat period (22 days) in the Indus basin.

Fig. 9: Niger basin showing Jason-2 ground tracks.

Fig. 10: Sentinel-3A and Sentinel-3B ground tracks over the Niger basin.

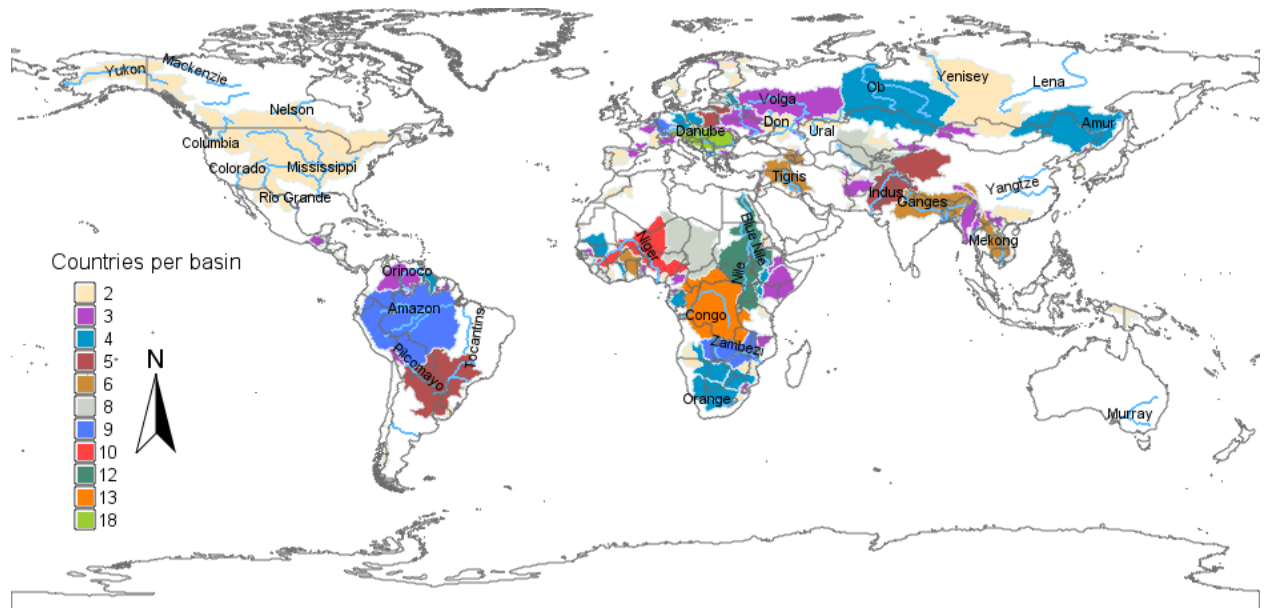
Fig. 11: Number of SWOT observations per repeat period (22 days) in the Niger basin.

## Tables

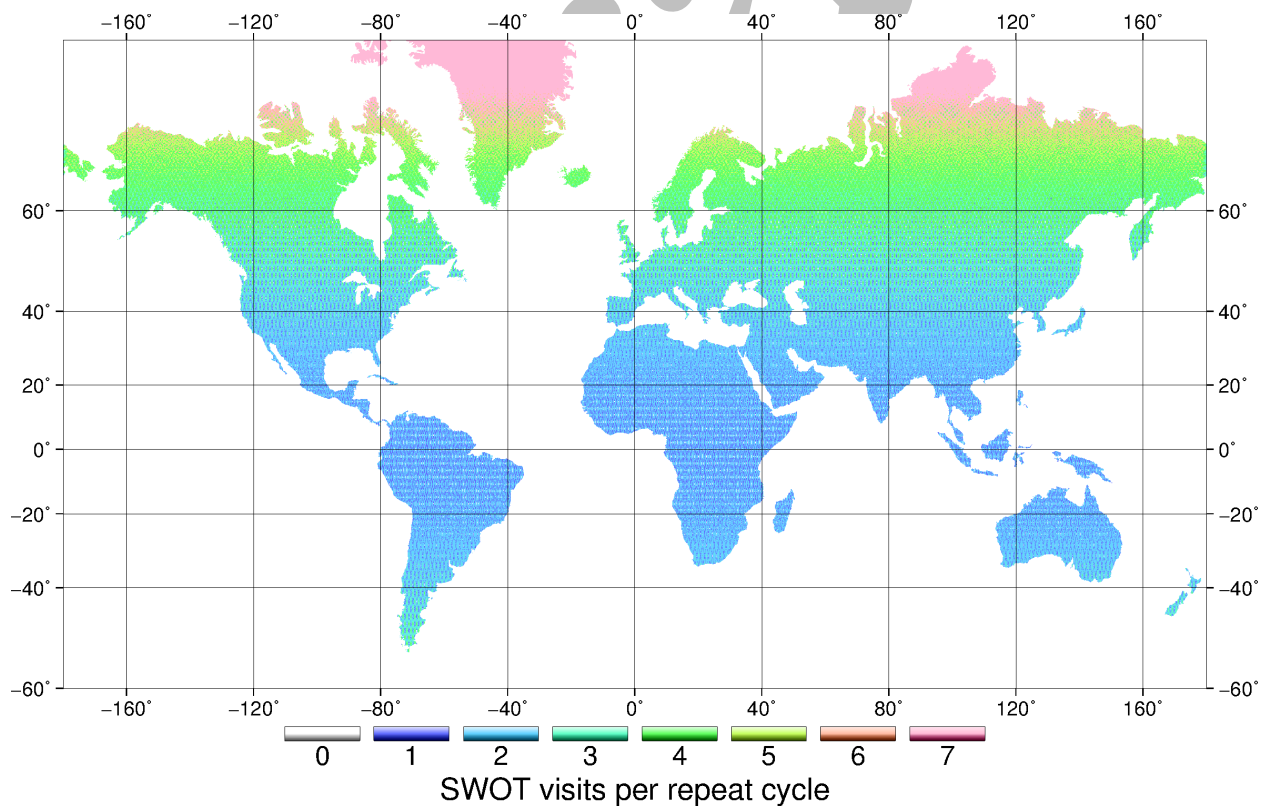
Minimum water body area seen	250 m <sup>2</sup>
Minimum river width seen	100 m
Height accuracy	< 10 cm (over 1 km <sup>2</sup> )
Slope accuracy	1 cm/km (over 10 km)
Water mask area error	<20% of the total water body area
Min. mission life time	3 years

Table 1.

# Figures



**Fig. 1**



**Fig. 2**

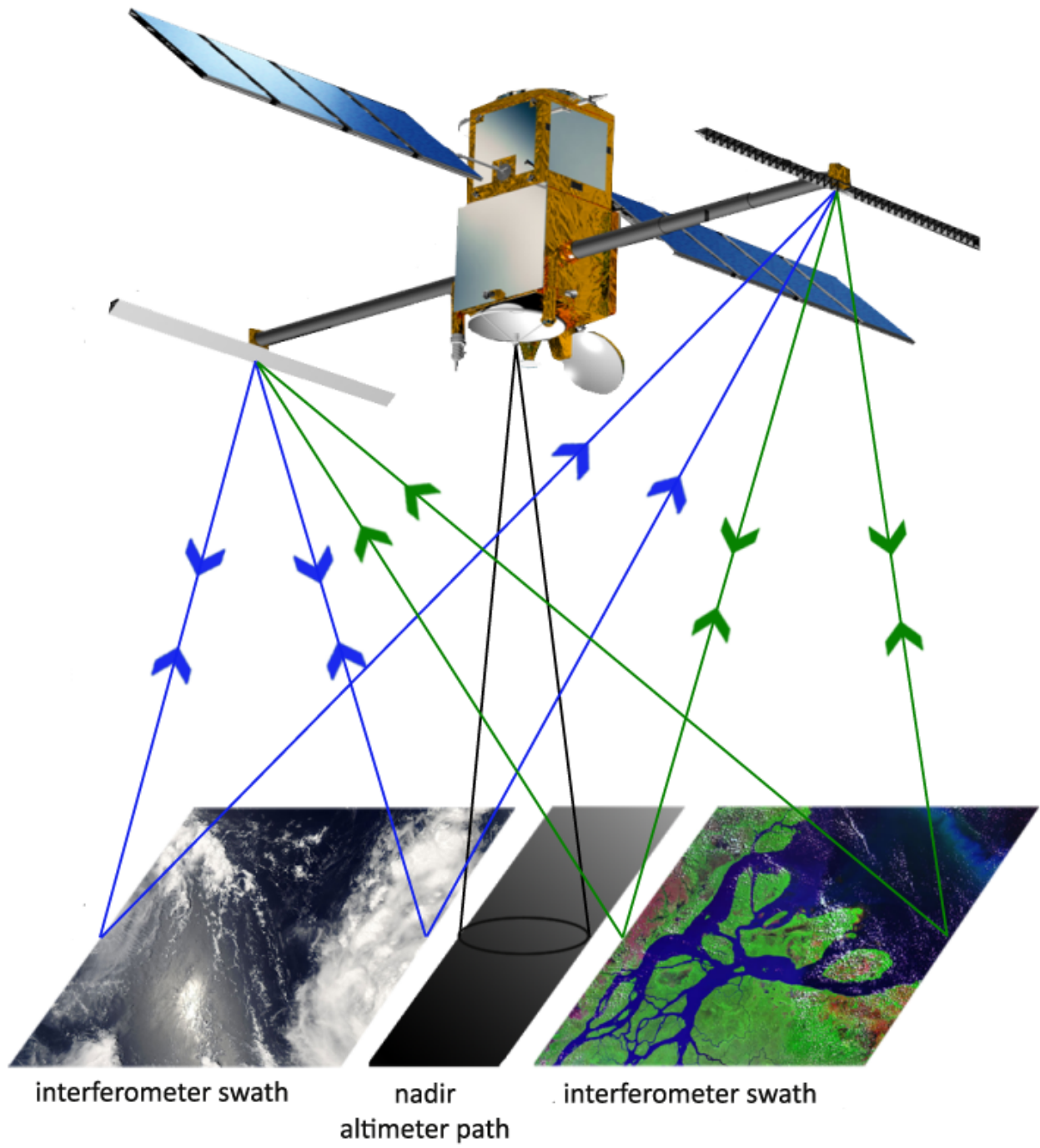


Fig. 3

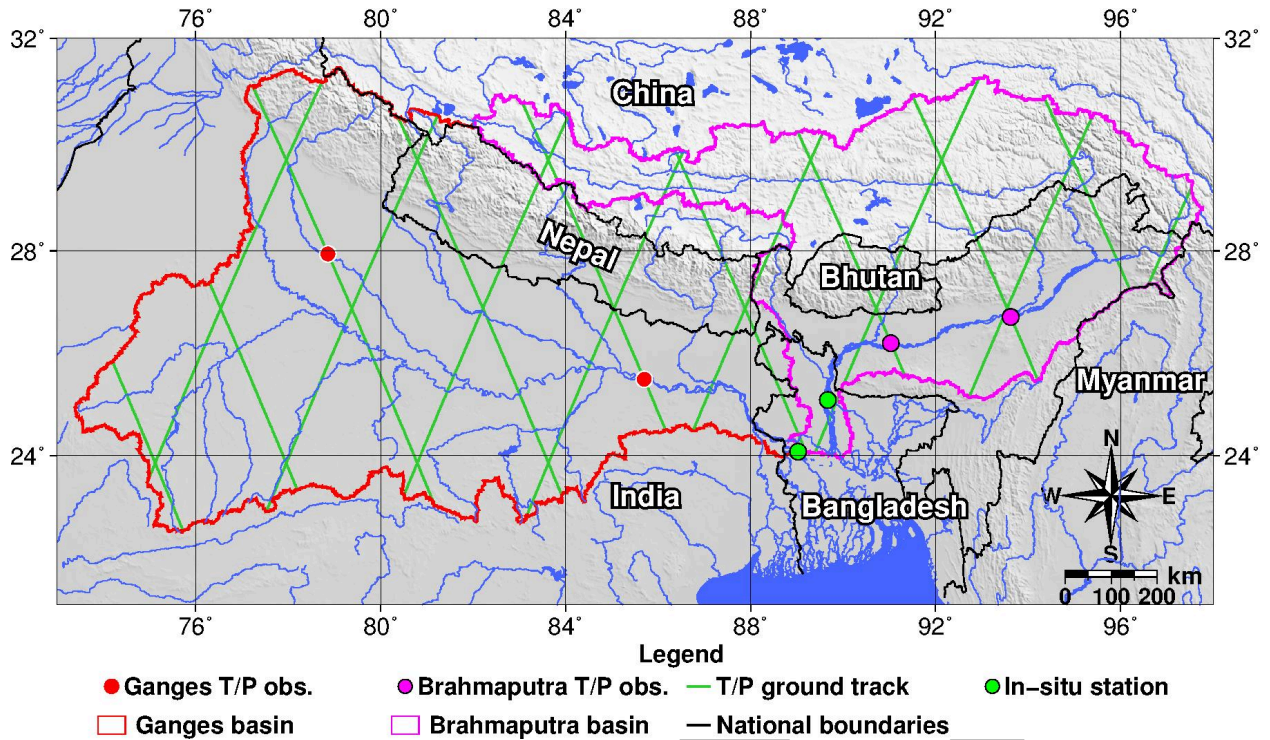


Fig. 4

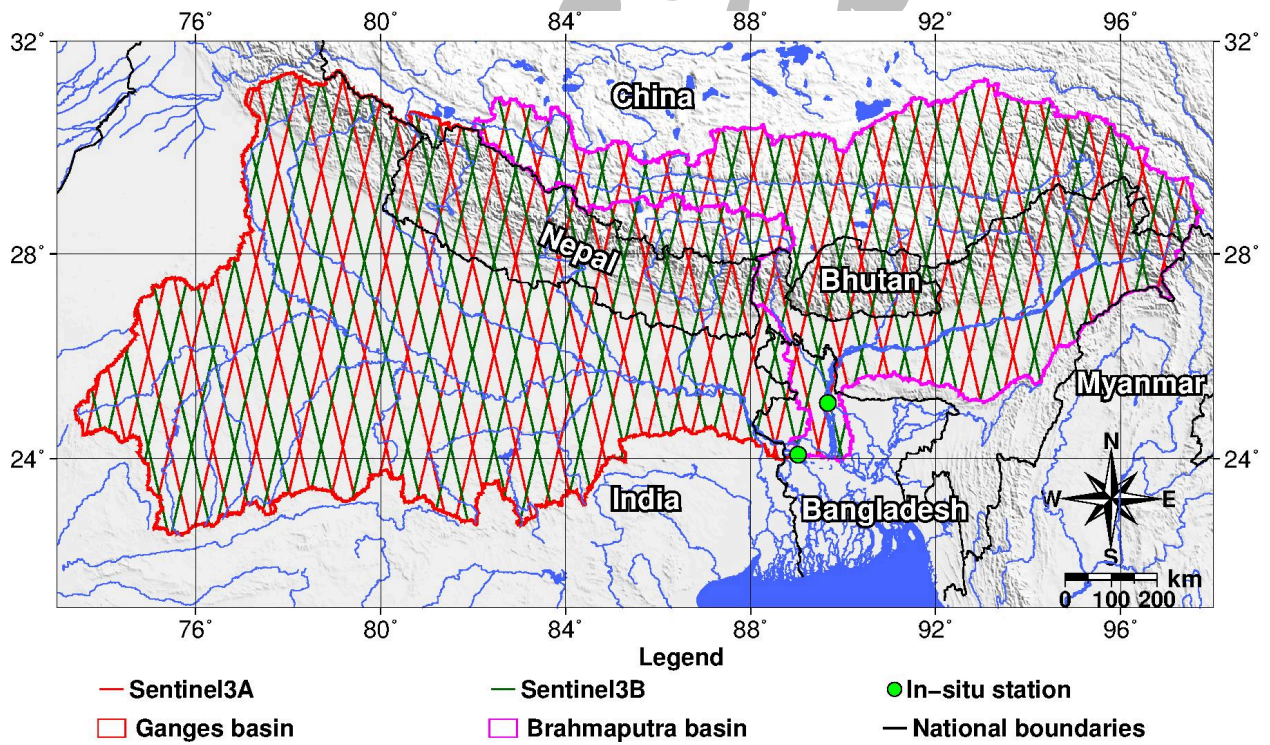


Fig. 5

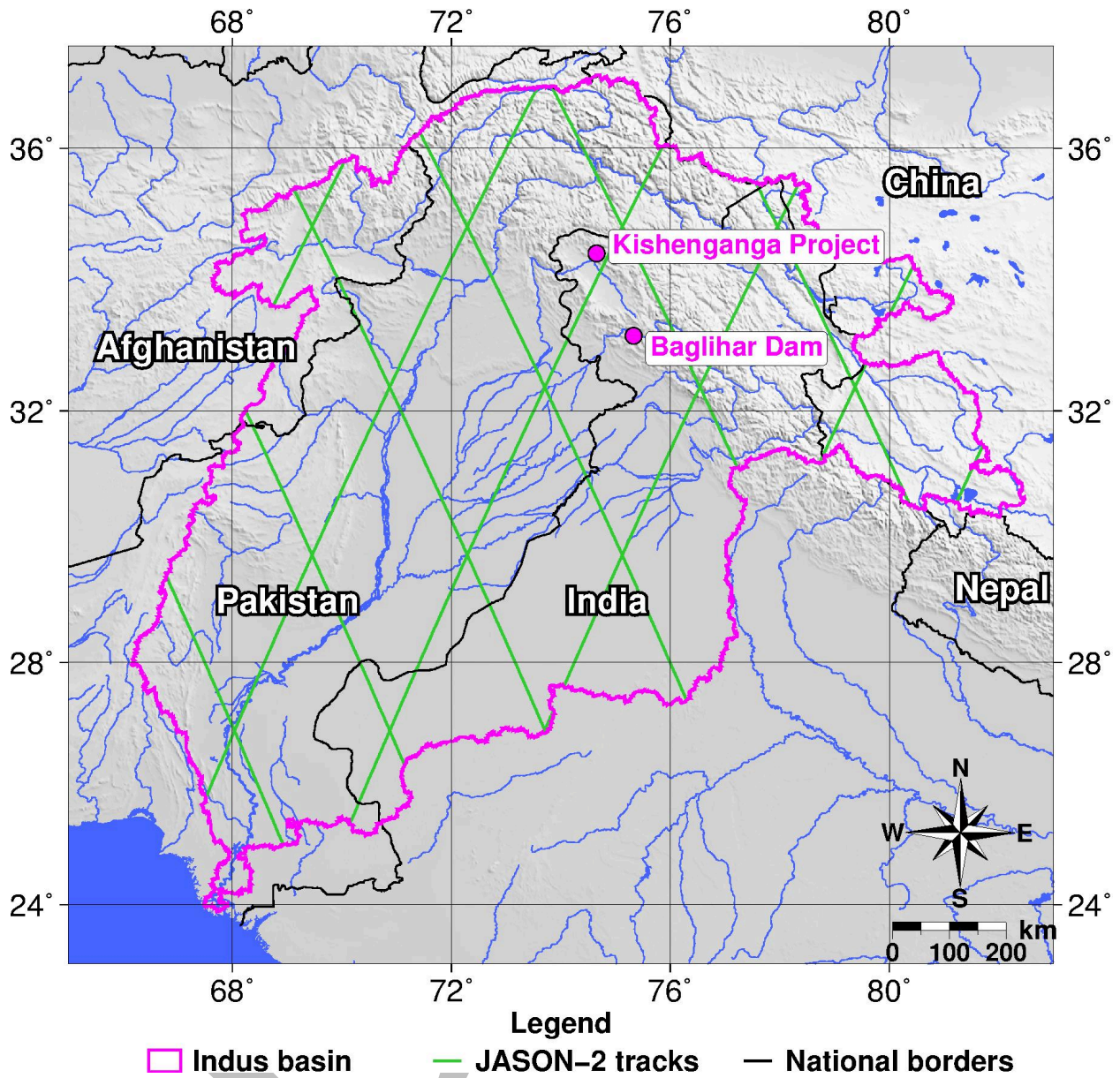
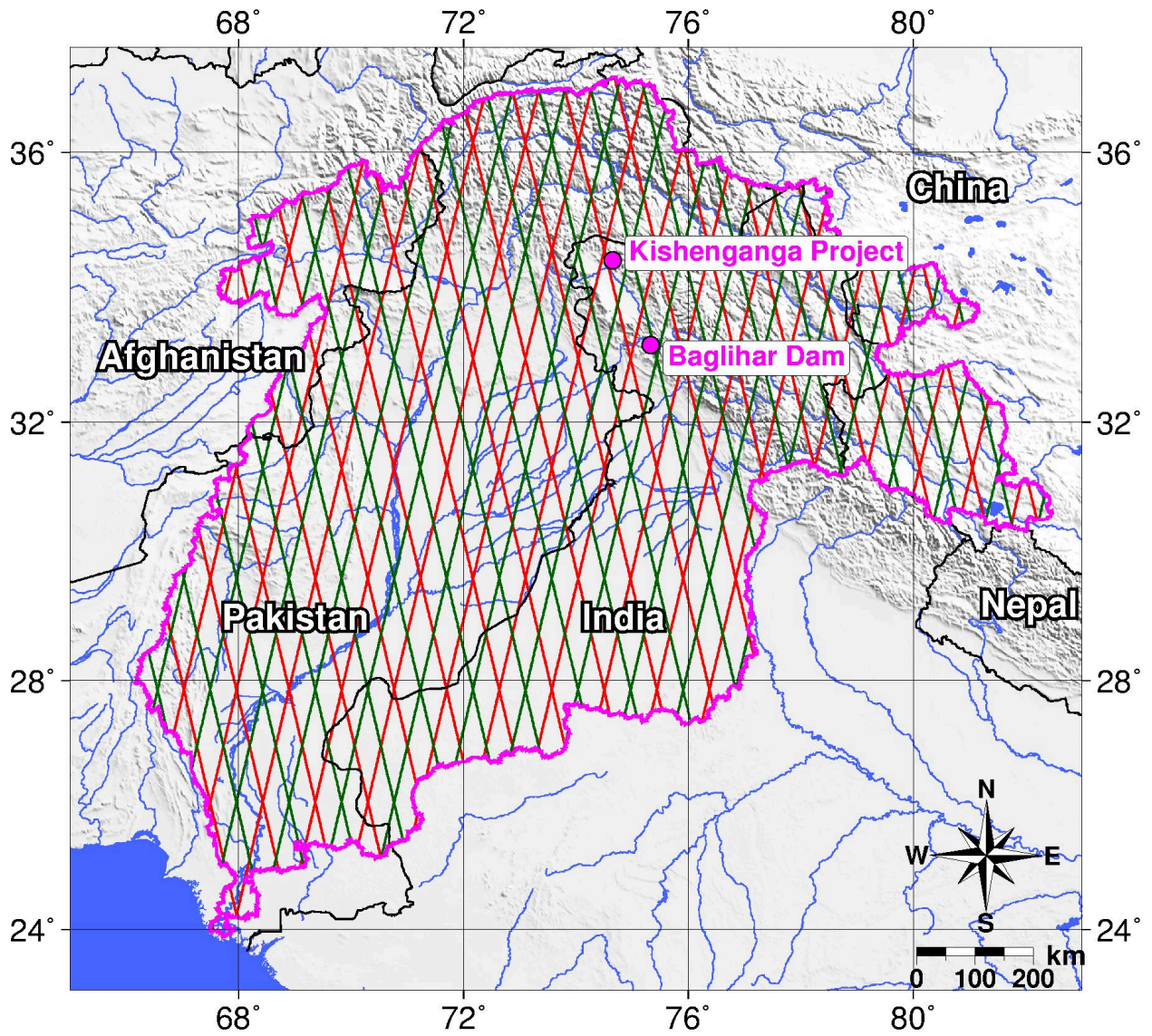


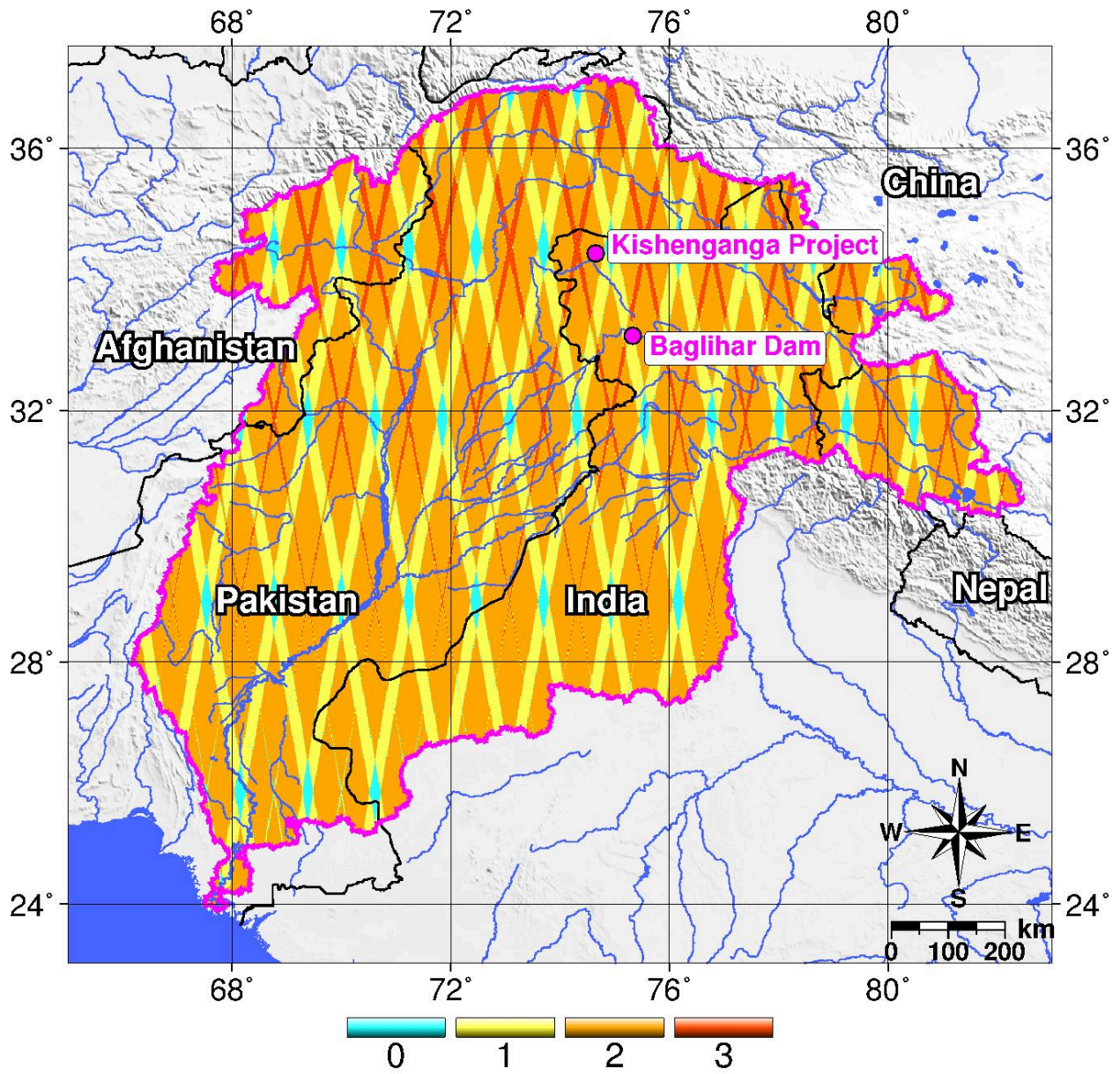
Fig. 6



**Legend**  
 □ Indus basin    — Sentinel3A    — Sentinel3B    — National borders

Fig. 7





Number of SWOT Observations

Fig. 8

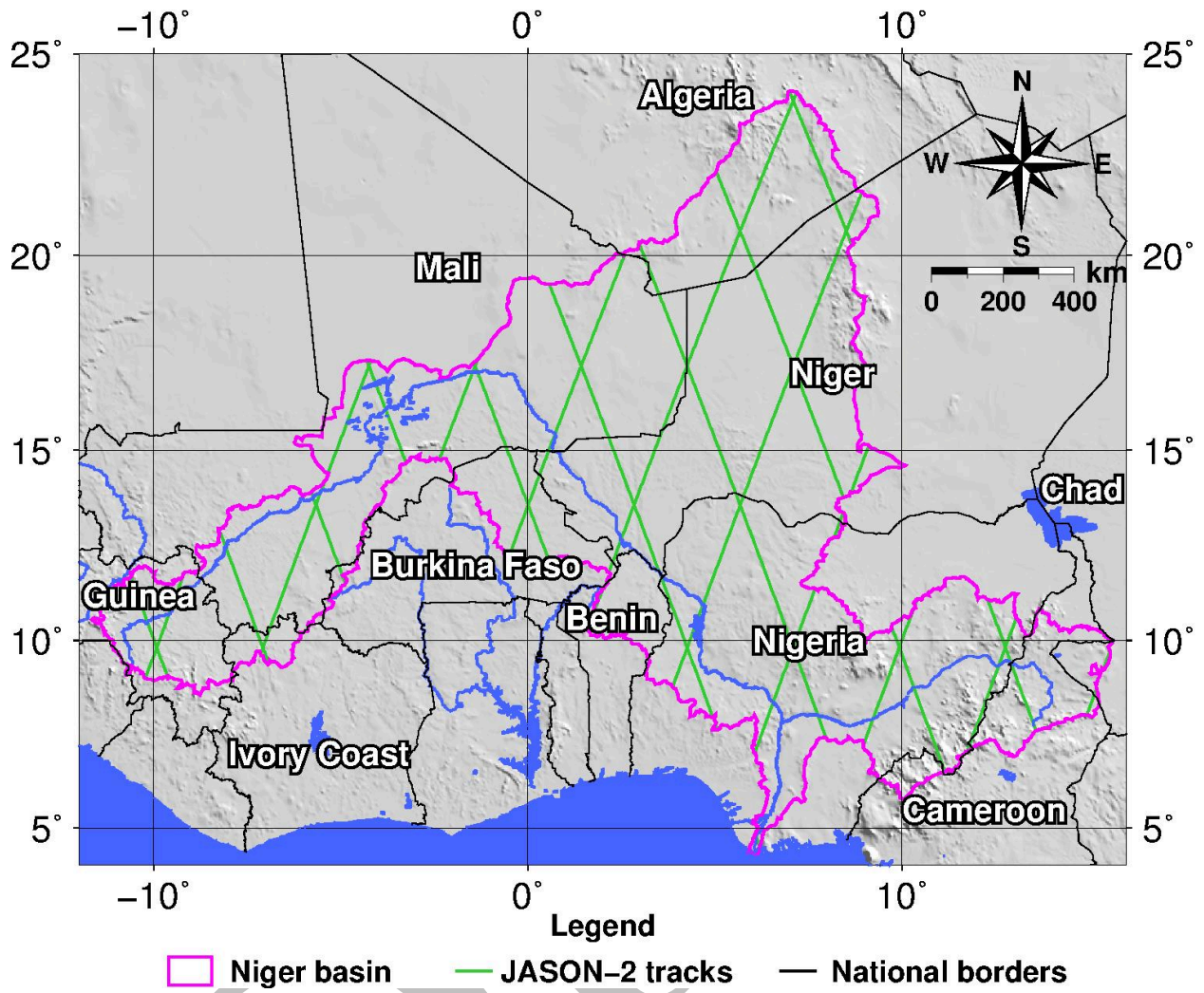


Fig. 9

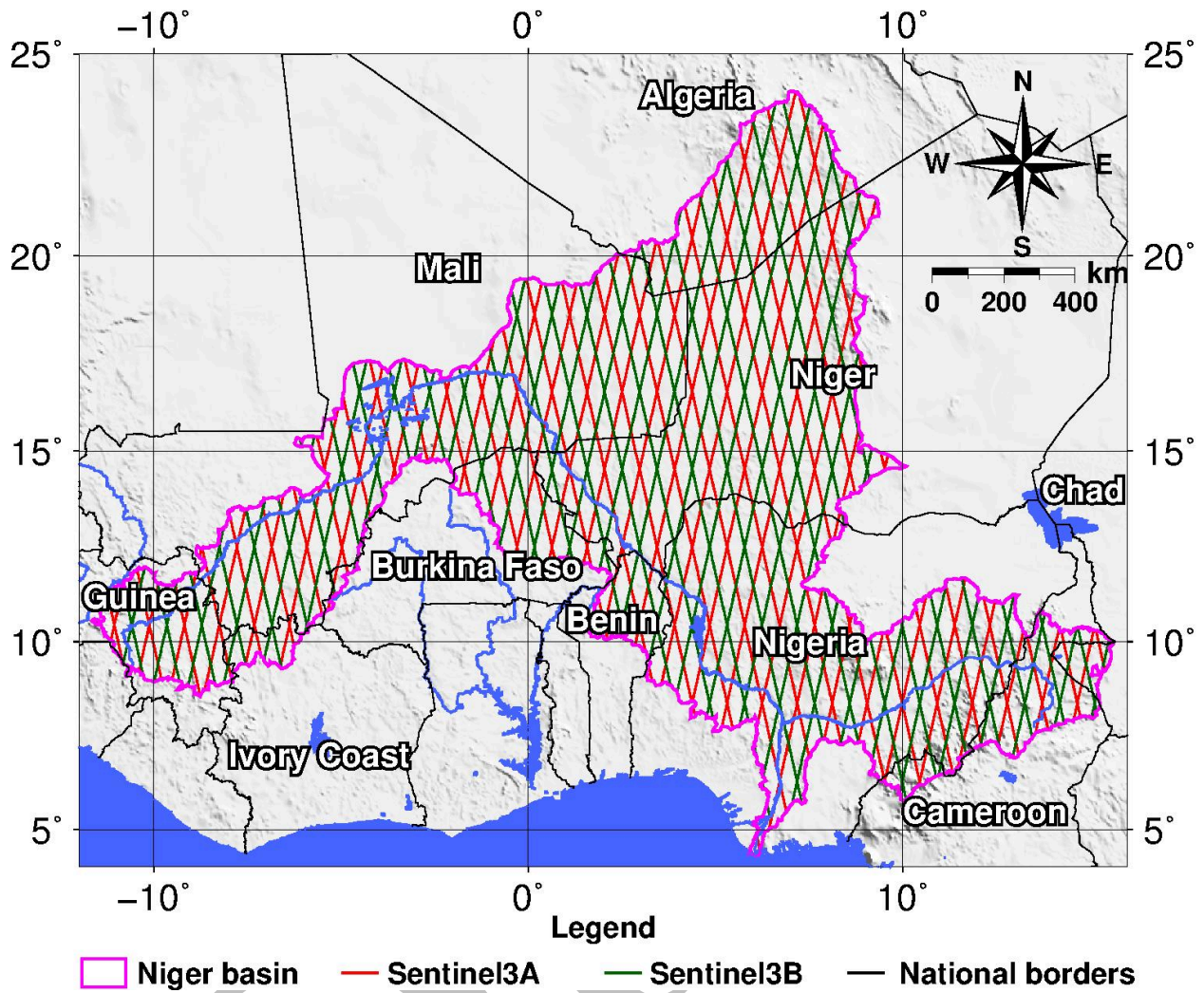
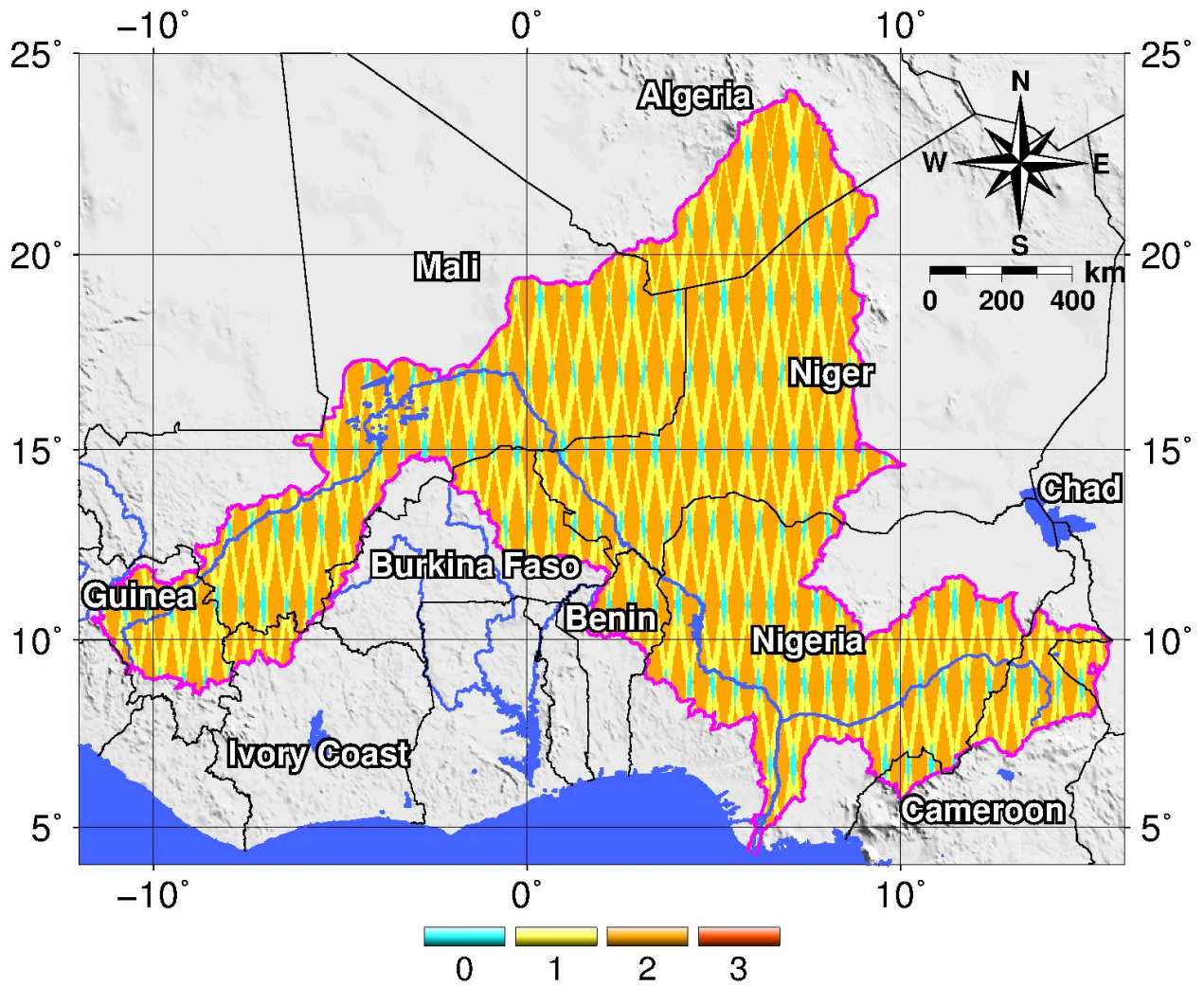


Fig. 10



Number of SWOT Observations

Fig. 11